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/******
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```
Read/write Control program for Ring bufer on EEPROM
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Programmed by Kenji Arai/JH1PJL
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E mail: kenjia@sannet.ne.jp jh1pjl@arrl.net
```

```
URL: http://www.page.sannet.ne.jp/kenjia/
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```
August 1,2004 Start coding
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```
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```

```
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```

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```
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```

```
*****/
```

```
/* ----< Include Files > ----- */
```

```
#include "rtm_H8_3664.h"
```

```
#include "ringbuf.h"
```

```
#include "iiceep.h"
```

```
#include "const.h"
```

```
#include "task.h"
```

```
/* ----< Function Prototype > ----- */
```

```
void ebzr(void); // Buzzer on = 1 or off =0
```

```
void eclearlap(void); // Clear lap data in EEPROM
```

```
void edisplay(void); // display lap data
```

```
void edsp_all_lap(void); // display all of lap data
```

```
void edsp_all_r_lap(void);
```

```
void edsp_all_both_lap(unsigned char);
```

```
void esetlapptr(void); // Set lap data pointer for latest
```

```
void ehelpp(void); // Help
```

```
void pick_data_of_lap(unsigned char);
```

```
void uschar2dec(unsigned char); // 1byte change to decimal ascii
```

```
void show_ptr(lap_ptr *); // Show EEPROM ringbuffer pointer information
```

```
/* ----< Function Prototype (Extern) > ----- */
```

```
extern void xerrcmd(void); // Command Error
```

```
extern char *eqstrf( char * , char * );
```

```
extern void formater4timer_dbl(unsigned long, char *, char);
```

```
extern void xedumpb( void );
```

```
extern unsigned long ogetdata( unsigned long );
```

```
extern void cmdsrch( void );
```

```
/* ----< RAM assign > ----- */
```

```
one_lap tmp_eep[4]; // temporary data buffer in RAM
```

```
// (0= SW), 1= IR, (2= MG), 3= read from EEPROM
```

```
unsigned int lap_bf_cnt; // pointer counter for above lap_data_buf[]
```

```
static lap_ptr tmp_eep_ptr;// temporary pointer buffer in RAM
```

```
static union { // ready status for Switch, InfraRed and Magnet
```

```
unsigned char BYTE; // Byte Access */
```

```
struct { // Bit Access */
```

```
unsigned char SW:1; // Bit 7 */
```

```

        unsigned char IR:1;          /* Bit 6 */
        unsigned char MG:1;          /* Bit 5 */
        unsigned char NON:5; /* Bit 4 to 0 */
    } BIT;
} lap_data_status;
unsigned char id_save;                // number of Lapdata
static union {                        // ready status for Switch, InfraRed and Magnet

    unsigned char BYTE;                /* Byte Access */
    struct {                            /* Bit Access */
        unsigned char TGLPR:1;        /* Bit 7 */
        unsigned char TGLPW:1;        /* Bit 6 */
        unsigned char MILPR:1;        /* Bit 5 */
        unsigned char MILPW:1;        /* Bit 4 */
        unsigned char TMPOR:1;        /* Bit 3 */
        unsigned char BZFGW:1;        /* Bit 2 */
        unsigned char BZFGR:1;        /* Bit 1 */
        unsigned char OSCCR:1;        /* Bit 0 */
    } BIT;
} eep_sys_rw;
unsigned char Device_id;
unsigned char eep_clr_flg;

/* -----< RAM assign (External data) > ----- */
// lap time
extern unsigned int latest_dt;        // which tool is used for latest data
extern unsigned long lap_ir; // Lap timer by using InfraRed sensor input
extern one_lap lap_for_led;          // Latest lap dat for LCD display
extern one_lap lap_data_buf[];       // lap data buffer from EEPROM
extern unsigned char lap_ptr_buf_top; // pointer for lap_data_buf[] top data
extern unsigned char eepdt_md;        // transfer complete flag, EEPROM to lap_data_buf[]
extern unsigned char eepdt_flg;       // transfer complete flag, EEPROM to lap_data_buf[]
extern unsigned long lap_best;        // best lap data
extern unsigned char bz_onoff_flg; // Buzzer On/Off control flag
extern char osc_cmp;                 // Xtal freq. offset

// monitor
extern char line[BFSZ], *lp;
extern char timbuf[20];
extern unsigned long datap;
extern unsigned int tim_usr2;        /* user timer no.2 */

/* -----< Constant > ----- */
/*          0          10          20          30          40          50 */
/*          012345678901234567890123456789012345678901234567890 */
char *const mntrmsg0 = " ----- Lap data control [?=H(ret)] -----";
//static char *const exitmsg = " Return to command? 'Y'(ret) or 'N'";
static char *const lap_msg = " No. ID By Laptime";
static char *const lpc_msg = " -- Continue? 'Y'(ret) or 'N'";
static char *const clr_msg0 = "Are your sure to clear EEPROM? 'Y'(ret) or 'N'";
static char *const clr_msg1 = "Cleared!";
static char *const clr_msg2 = "Canceled";
static char *const helpmsgB = " B Buzzer on = 1 or off =0";
static char *const helpmsgC = " C Clear Lap data in EEPROM";
static char *const helpmsgD = " D Display lap data (new to old)";
static char *const helpmsgDR = " DR Display lap data (old to new)";
static char *const helpmsgE = " E Dump EEPROM contents";
static char *const helpmsgM = " M Go to H8 Monitor";

```

```

static char *const helpmsgH = "  H      You know this";
/*
                                01234567890123456789012345678901234567890 */

/* ----< Control program > ----- */
//
//      Data control routine for EEPROM Read/Write for Lapdata
//
//
//
// EEPROM Read/Write analysis
void IdleEEP( void )
{
    unsigned long dt;
    unsigned int  addr;
    unsigned char i;

    if (lap_data_status.BYTE){
        if (lap_data_status.BIT.IR == 1){
            tmp_eep[IR_LAP].laptim = lap_ir;    // save lap time into temp. buff
            tmp_eep[IR_LAP].msr_mode = IR_LAP; // save masured tool
            tmp_eep[IR_LAP].id = ++id_save;     // save new(+1) id
            ring_put_data(&tmp_eep_ptr, &tmp_eep[IR_LAP]);
            lap_data_status.BIT.IR = 0;
            lap_for_led = tmp_eep[IR_LAP];
            latest_dt = 0x80 + IR_LAP;
            return;
        }
    }
    if (eepdt_flg == REQUEST){
        pick_data_of_lap(eepdt_md);           // pick up measured tool(SW,IR,MG)
        eepdt_flg = READY;                   // Ready to read data in buffer
    }
    if (eep_sys_rw.BYTE != 0){
        if (eep_sys_rw.BIT.TGLPR == 1){
            rd_eep_trg();
        } else if (eep_sys_rw.BIT.TGLPW == 1){
            eep_sys_rw.BIT.TGLPW = 0;
            addr = EEP_BSTLAP;
            dt = lap_best;
            i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 1677216));
            i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 65536));
            i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256));
            i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt));
        } else if (eep_sys_rw.BIT.BZFGW == 1){
            rd_eep_bz();
        } else if (eep_sys_rw.BIT.BZFGW == 1){
            eep_sys_rw.BIT.BZFGW = 0;
            addr = EEP_BZONOF;
            i = Write_byte_EEPROM((unsigned short)addr, bz_onoff_flg);
        }
    }
    if (eep_clr_flg == 1){
        eep_clr_flg = 0;
        if (ring_is_empty(&tmp_eep_ptr)){ // check buffer empty
            ;
        } else { // not empty
            ring_clear(&tmp_eep_ptr);
        }
    }
}

```

```

    }
}

void init_eep_lap(void)
{
    // EEPROM I/F
    Init_eeprom();           // Initialize EEPROM with port on/off mode
    Init_iic2();            // Initialize IIC2 I/F
    Device_id = 0x00;       // Set slave address of EEPROM: 0 (A2,A1,A0)
    // Clear buffer
    tmp_eep[0].laptim = 0;
    tmp_eep[0].msr_mode = 0; // save masured tool
    tmp_eep[0].id = 0;       // save new(+1) id
    tmp_eep[1].laptim = 0;   // save lap time into temp. buff
    tmp_eep[1].msr_mode = 0; // save masured tool
    tmp_eep[1].id = 0;       // save new(+1) id
    tmp_eep[2].laptim = 0;   // save lap time into temp. buff
    tmp_eep[2].msr_mode = 0; // save masured tool
    tmp_eep[2].id = 0;       // save new(+1) id
    tmp_eep[3].laptim = 0;   // save lap time into temp. buff
    tmp_eep[3].msr_mode = 0; // save masured tool
    tmp_eep[3].id = 0;       // save new(+1) id
    lap_data_buf[0].laptim = TIM_EMPTY;
    lap_data_buf[0].msr_mode = NOTDATA;
    lap_data_buf[0].id = NOTDATA;
    eep_sys_rw.BYTE = 0;
    eep_clr_flg = 0;
    lap_data_status.BYTE = 0;
    ring_init(&tmp_eep_ptr);
    if (ring_rd_ptr_top(&tmp_eep_ptr)){
        id_save = 0; // if EEPROM is empty, clear id
        return;
    }
    ring_get_data(&tmp_eep_ptr, &tmp_eep[RD_LAP]);
    id_save = tmp_eep[RD_LAP].id; // read id and save it into RAM
    // Data read from EEPROM move to task.c general initialize routine
    // rd_eep_trg(); // read best lap data from EEPROM
    // rd_eep_bz(); // read buzzer flag from EEPROM
}

```

```

void rd_eep_trg(void)
{
    unsigned long dt;
    unsigned int  addr;

    eep_sys_rw.BIT.TGLPR = 0;
    addr = EEP_BSTLAP;
    dt = (unsigned long)Read_byte_EEPROM((unsigned short)addr++) * 16777216;
    dt += (unsigned long)Read_byte_EEPROM((unsigned short)addr++) * 65536;
    dt += (unsigned long)Read_byte_EEPROM((unsigned short)addr++) * 256;
    dt += (unsigned long)Read_byte_EEPROM((unsigned short)addr++);
    lap_best = dt & TIM_MAX_TR_MASK;
}

```

```

void rd_eep_osc(void)
{
    eep_sys_rw.BIT.OSCCR = 0;
}

```

```

    osc_cmp = (char)Read_byte_EEPROM((unsigned short)EEP_CLKCMP);
}

void rd_eep_bz(void)
{
    eep_sys_rw.BIT.BZFGR = 0;
    bz_onoff_flg = (unsigned char)Read_byte_EEPROM((unsigned short)EEP_BZONOF);
}

void ready_sw_data(void)
{
    lap_data_status.BIT.SW = 1;
}

void ready_ir_data(void)
{
    lap_data_status.BIT.IR = 1;
}

void ready_mg_data(void)
{
    lap_data_status.BIT.MG = 1;
}

void req_lapdata_clear(void)
{
    eep_clr_flg = 1;
}

void req_rd_tglap(void)
{
    eep_sys_rw.BIT.TGLPR = 1;
}

void req_wr_tglap(void)
{
    eep_sys_rw.BIT.TGLPW = 1;
}

void req_rd_milap(void)
{
    eep_sys_rw.BIT.MILPR = 1;
}

void req_wr_milap(void)
{
    eep_sys_rw.BIT.MILPW = 1;
}

void req_rd_bzfg(void)
{
    eep_sys_rw.BIT.BZFGR = 1;
}

void req_wr_bzfg(void)
{
    eep_sys_rw.BIT.BZFGW = 1;
}

```

```

void req_rd_osccmp(void)
{
    eep_sys_rw.BIT.OSCCR = 1;
}

void pick_data_of_lap(unsigned char md)
{
    unsigned char i, skip;

    if (ring_is_empty(&tmp_eep_ptr)){ // check buffer empty
        lap_data_buf[0].laptim = TIM_EMPTY;
        lap_data_buf[0].msr_mode = NOTDATA;
        lap_data_buf[0].id = NOTDATA;
        return;
    }
    ring_rd_ptr_top(&tmp_eep_ptr);
    skip = lap_ptr_buf_top;
    if (skip){
        for (i = 0; i < skip;){
            ring_get_data(&tmp_eep_ptr, &tmp_eep[RD_LAP]);
            if (tmp_eep[RD_LAP].msr_mode == md){
                i++;
            }
            if (ring_rd_ptr_nxt(&tmp_eep_ptr)){
                lap_data_buf[0].laptim = TIM_EMPTY;
                lap_data_buf[0].msr_mode = NOTDATA;
                lap_data_buf[0].id = NOTDATA;
                return;
            }
        }
    }
    for (i = 0; i < SCRNSIZ;){
        ring_get_data(&tmp_eep_ptr, &tmp_eep[RD_LAP]);
        if (tmp_eep[RD_LAP].msr_mode == md){
            lap_data_buf[i] = tmp_eep[RD_LAP];
            i++;
        }
        if (ring_rd_ptr_nxt(&tmp_eep_ptr)){
            lap_data_buf[i].laptim = TIM_EMPTY;
            lap_data_buf[i].msr_mode = NOTDATA;
            lap_data_buf[i].id = NOTDATA;
            return;
        }
    }
}

/////////////////////////////////////////////////////////////////
//      Part of monitor function for EEPROM control
/////////////////////////////////////////////////////////////////
/* -----Command Table ----- */
typedef const struct{
    char    *cmd;
    void    (*func)( void );
}TBLENTY;

TBLENTY ecmdtbl[] = {
    {"B",ebzr}, // Buzzer on = 1 or off =0

```

```

    {"C",eclearlap},          // Clear lap data in EEPROM
// {"DN",edisplay},         // Display one lap data
    {"DR",edsp_all_r_lap},   // Display all lap data
    {"D",edsp_all_lap},      // Display all lap data
    {"E",xedumpb},           // Dump EEPROM
    {"M",cmdsrch},          // H8 Monitor
// {"SP",esetlapptr},       // Set lap data pointer for latest
    {"H",ehelp},             // Help
    {"%0",xerrcmd},         // Command Error */
};

```

```
/* -----Help ----- */
```

```
void ehelp( void )
```

```

{
    SciPutS( helpmsgB ); PutCRLF();
    SciPutS( helpmsgC ); PutCRLF();
    SciPutS( helpmsgD ); PutCRLF();
    SciPutS( helpmsgDR); PutCRLF();
    SciPutS( helpmsgE ); PutCRLF();
    SciPutS( helpmsgM ); PutCRLF();
    SciPutS( helpmsgH ); PutCRLF();
/*
    SciPutS(" B      Buzzer on = 1 or off =0");          PutCRLF();
    SciPutS(" C      Clear Lap data in EEPROM");          PutCRLF();
    SciPutS(" D      Display lap data (new to old)"); PutCRLF();
    SciPutS(" DR     Display lap data (old to new)"); PutCRLF();
//   SciPutS(" DN    Display newest");                      PutCRLF();
    SciPutS(" E      Dump EEPROM contents");              PutCRLF();
    SciPutS(" M      Go to H8 Monitor");                  PutCRLF();
//   SciPutS(" SP    Set lapdata pointer for latest");    PutCRLF();
    SciPutS(" H      You know this");                    PutCRLF();
//   SciPutS(" [RET] Return to called routine");          PutCRLF();
*/
}

```

```
/* ----Command analysis and excute ---- */
```

```
void lap_cmd_srch( void )
```

```

{
    char *c;
    TBLENTY *p;

    SciPutS( mntrmsg0 );
    for(;;){
        PutCRLF();
        SciPutC('>');
        getline();
/*
        if(line[0] == '%0'){
            SciPutS( exitmsg );
            getline();

            if((line[0] == '%0') || (line[0] == 'Y')){
                PutCRLF();
                opning_msg();
                return;
            } else {
                continue;
            }
}

```

```

        }
*/
        for(p = ecmdtbl; *p > cmd; p++){
            if((c = eqstrf(p > cmd,lp)) != 0){
                break;
            }
        }
        lp = c;
        (*p > func)();
    }
}

/* -----Buzzer on = 1 or off =0 ----- */
void ebzr()
{
    skpspc();
    if (ogetdata( datap ) == 0){
        SciPutS(" Buzzer OFF");      PutCRLF();
        bz_onoff_flg = OFF;
    } else {
        SciPutS(" Buzzer ON");      PutCRLF();
        bz_onoff_flg = ON;
        tim_usr2 = T_500MS;          // for Buzzer ON longer time!!
    }
    req_wr_bzfg();
}

/* -----Clear lap data in EEPROM ----- */
void eclearlap()
{
    SciPutS( clr_msg0 );
    getline();

    if((line[0] == '\0') || (line[0] == 'Y')){
        SciPutS( clr_msg1 );
        ring_clear(&tmp_eep_ptr);
        show_ptr(&tmp_eep_ptr);
        return;
    } else {
        SciPutS( clr_msg2 );
    }
}

/* -----Show pointer data ----- */
void show_ptr(lap_ptr *ptr)
{
    unsigned int dt;

    SciPutS(" EEPROM ring buffer pointer (HEX)");      PutCRLF();
    dt = (unsigned int)ptr >buf_top;
    SciPutS(" Buffer top = ");
    puthxw(dt);
    dt = (unsigned int)ptr >head;
    SciPutS(", head = ");
    puthxw(dt);
    dt = (unsigned int)ptr >tail;
    SciPutS(", tail = ");
}

```



```

    puthxw(dt);
    dt = (unsigned int)ptr >size;
    SciPutS(", size = ");
    puthxw(dt);
    PutCRLF();
}

/* -----Show Lap data ----- */
void edisplayap()
{
    if (ring_is_empty(&tmp_eep_ptr)){ // check buffer empty
        SciPutS(" EEPROM is empty "); PutCRLF();
        return;
    }
    ring_get_data(&tmp_eep_ptr, &tmp_eep[RD_LAP]);
    SciPutS(" Lap time = ");
    (tmp_eep[RD_LAP].laptim, timbuf, 1);
    SciPutS(timbuf);
    SciPutS(", measured by ");
    if (tmp_eep[RD_LAP].msr_mode == SW_LAP){
        SciPutS("SW");
    } else if (tmp_eep[RD_LAP].msr_mode == IR_LAP){
        SciPutS("IR");
    } else if (tmp_eep[RD_LAP].msr_mode == MG_LAP){
        SciPutS("MG");
    } else {
        SciPutS("??");
    }
    SciPutS(", ID =");
    puthxb(tmp_eep[RD_LAP].id);
    PutCRLF();
}

/* -----Show All of Lap data ----- */
void edsp_all_lap()
{
    edsp_all_both_lap(1);
}

void edsp_all_r_lap()
{
    edsp_all_both_lap(0);
}

void edsp_all_both_lap(unsigned char flg)
{
    unsigned char n, i;

    n = 1;
    SciPutS(lap_msg); PutCRLF();
    if (ring_is_empty(&tmp_eep_ptr)){ // check buffer empty
        SciPutS(" EEPROM is empty "); PutCRLF();
        return;
    }
    if (flg){
        ring_rd_ptr_top(&tmp_eep_ptr);
    } else {
        ring_rd_ptr_end(&tmp_eep_ptr);
    }
}

```



```

//
//  subroutine for EEPROM control
//
///////////////////////////////////////////////////////////////////
// clear EEPROM buffer
int ring_clear (lap_ptr *ring)
{
    ring->buf_top = EEP_LAP_TOP;
    ring->size = LAP_DT_SZ;
    ring->head = ring->tail = ring->rd_ptr = ring->buf_top;
    id_save = 0; // if EEPROM is empty, clear id
    return(ring_ptr_save(ring));
}

// pointer initialize for next power on
int ring_init(lap_ptr *ring)
{
    return(ring_ptr_load(ring)); // data pointer read from EEPROM
}

// pointer initialize for data read
int ring_rd_ptr_top(lap_ptr *ring)
{
    ring->rd_ptr = ring->tail; // set latest pointer
    if (ring_rd_ptr_nxt(ring)){ // if empty, return with error
        return -1;
    }
    return 0; // normal end
}

int ring_rd_ptr_end(lap_ptr *ring)
{
    ring->rd_ptr = ring->head; // set latest pointer
    return 0; // normal end
}

// pointer change to next read
int ring_rd_ptr_nxt(lap_ptr *ring)
{
    unsigned int i;

    if (ring->rd_ptr == ring->head){ // if current pointer is bottom(older) then
        return -1;
    }
    return w/ error
}
i = (unsigned int)ring->rd_ptr - SIZ;
// check next pointer
if ( (i < (unsigned int)ring->buf_top) || (i > (unsigned int)ring->buf_top + ring->size)){
    ring->rd_ptr = (void *)((unsigned int)ring->buf_top + ring->size - SIZ);
} else {
    ring->rd_ptr = (void *)i;
}
return 0;
}

int ring_rd_ptr_nxt_r(lap_ptr *ring)
{
    unsigned int i;

```

```

    i = (unsigned int)ring->tail - SIZ;
    if (i == (unsigned int)ring->rd_ptr){
        return -1; // if current pointer is bottom(older) then
return w/ error
    }
    i = (unsigned int)ring->rd_ptr + SIZ;
    // check next pointer
    if ( i == (unsigned int)ring->buf_top + ring->size){
        ring->rd_ptr = ring->buf_top;
    } else {
        ring->rd_ptr = (void *)i;
    }
    return 0;
}

// check empty condition
int ring_is_empty(lap_ptr *ring)
{
    if (ring->head == ring->tail){
        return 1;
    }
    return 0;
}

// check read pointer
int ring_is_end(lap_ptr *ring)
{
    if (ring->head == ring->rd_ptr){
        return 1;
    }
    return 0;
}

// write data into the buffer
int ring_put_data(lap_ptr *ring, one_lap *data)
{
    unsigned int pt0,pt1;

    ring_data_save(ring, data);
    // set next pointer
    pt0 = (unsigned int)ring->tail + SIZ;
    pt1 = (unsigned int)ring->buf_top + ring->size;
    if (pt0 == pt1){ // if reach EEPROM ring buffer end, then set to top
        ring->tail = ring->buf_top;
    } else { // not reach buf. end yet
        ring->tail = (void *)pt0;
    }
    // if buffer is reached full, then modify head pointer
    if ( ring->tail == ring->head){ // full condition then action
        pt0 = (unsigned int)ring->head + SIZ;
// pt1 = (unsigned int)ring->buf_top + ring->size; // calculated by above
        if (pt0 == pt1){ // if reach EEPROM ring buffer end, then set to top
            ring->head = ring->buf_top;
        } else { // not reach buf. end yet
            ring->head = (void *)pt0;
        }
    }
}

```

```

    ring_ptr_save(ring);
    return 0;
}

// read data from the buffer
int ring_get_data(lap_ptr *ring, one_lap *data)
{
    ring_data_load(ring, data);
    return 0;
}

// check how many data in the buffer
int ring_get_capacity(lap_ptr *ring)
{
    if (ring->head < ring->tail) {
        return ((unsigned int)ring->tail - (unsigned int)ring->head);
    }
    return (unsigned int)ring->size;
}

// pointer save action into EEPROM
int ring_ptr_save(lap_ptr *ring)
{
    unsigned int addr, dt;
    unsigned char i;

    // addr
    addr = EEP_PTR;
    // buffer top addr
    dt = (unsigned int)ring->buf_top;
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256));
// if (error_status == ERROR){
//     ;
// }
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)dt );
    // data head(older)
    dt = (unsigned int)ring->head;
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256));
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)dt );
    // data tail(latest)
    dt = (unsigned int)ring->tail;
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256));
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)dt );
    // data pointer for data read
    dt = (unsigned int)ring->rd_ptr;
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256));
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)dt );
    // EEPROM ring buffer size
    dt = ring->size;
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256));
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)dt );
    return 0;
}

// pointer read action from EEPROM
int ring_ptr_load(lap_ptr *ring)
{
    unsigned int addr;

```

```

unsigned char i, dt, dt0;

// addr
addr = EEP_PTR;
// buffer top addr
dt0 = Read_byte_EEPROM((unsigned short)addr++);
// if (error_status == ERROR){
//     ;
// }
dt = Read_byte_EEPROM((unsigned short)addr++);
ring->buf_top = (void *)((unsigned int)dt0 * 256 + (unsigned int)dt);
// data head(older)
dt0 = Read_byte_EEPROM((unsigned short)addr++);
dt = Read_byte_EEPROM((unsigned short)addr++);
ring->head = (void *)((unsigned int)dt0 * 256 + (unsigned int)dt);
// data tail(latest)
dt0 = Read_byte_EEPROM((unsigned short)addr++);
dt = Read_byte_EEPROM((unsigned short)addr++);
ring->tail = (void *)((unsigned int)dt0 * 256 + (unsigned int)dt);
// data pointer for data read
dt0 = Read_byte_EEPROM((unsigned short)addr++);
dt = Read_byte_EEPROM((unsigned short)addr++);
ring->rd_ptr = (void *)((unsigned int)dt0 * 256 + (unsigned int)dt);
// EEPROM ring buffer size
dt0 = Read_byte_EEPROM((unsigned short)addr++);
dt = Read_byte_EEPROM((unsigned short)addr++);
ring->size = (unsigned int)dt0 * 256 + (unsigned int)dt;
return 0;
}

// data write action into EEPROM
int ring_data_save(lap_ptr *ring, one_lap *data)
{
    unsigned long dt;
    unsigned int addr;
    unsigned char i;

    // addr
    addr = (unsigned int)ring->tail;
    // lap time
    dt = data->laptim;
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 16777216)); // 2^24
// if (error_status == ERROR){
//     ;
// }
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 65536)); // 2^16
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt / 256)); // 2^8
    i = Write_byte_EEPROM((unsigned short)addr++, (unsigned char)(dt)); // 2^0
    // measured tool
    i = Write_byte_EEPROM((unsigned short)addr++, data->msr_mode);
    // id number
    i = Write_byte_EEPROM((unsigned short)addr++, data->id);
    return 0;
}

// data read action from EEPROM
int ring_data_load(lap_ptr *ring, one_lap *data)
{

```

```
unsigned int addr;
unsigned char i, dt,dt0,dt1,dt2;

// addr
addr = (unsigned int)ring->rd_ptr;
// lat time
dt2 = Read_byte_EEPROM((unsigned short)addr++);
dt1 = Read_byte_EEPROM((unsigned short)addr++);
dt0 = Read_byte_EEPROM((unsigned short)addr++);
dt = Read_byte_EEPROM((unsigned short)addr++);
data->laptim = (unsigned long)dt2 * 16777216 + (unsigned long)dt1 * 65536
              + (unsigned long)dt0 * 256 + (unsigned long)dt;
// measured tool
data->msr_mode = Read_byte_EEPROM((unsigned short)addr++);
// id number
data->id = Read_byte_EEPROM((unsigned short)addr++);
return 0;
}
```